

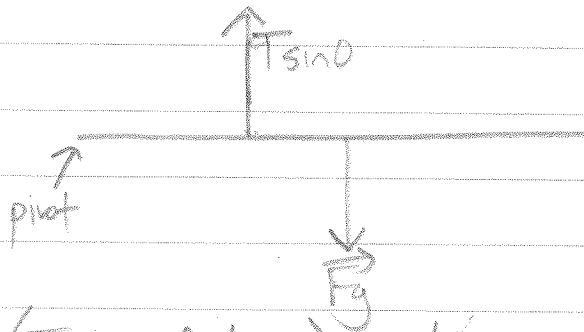
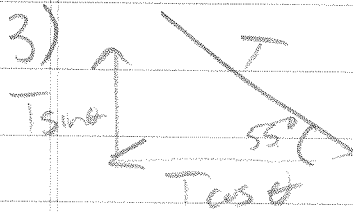
Torque + Rotation Review

1) $\tau = \vec{F} \cdot d$

$\rightarrow \tau = (250.0\text{N}) \cdot (.540\text{m}) = 135\text{N}$

2) $\tau = F_{\perp} \cdot d$

$\tau = F \cdot d \cdot \sin 30^{\circ}$



$\Sigma \tau = 0 \text{ N}\cdot\text{m} = (T \sin 55^{\circ} \cdot 1.6\text{m}) = (500\text{N} \cdot 2.0\text{m})$

$\rightarrow T = \frac{500\text{N} \cdot 2.0\text{m}}{(\sin 55^{\circ}) \cdot 1.6\text{m}} = 763\text{N}$

4) $\tau = I \cdot \alpha = mr^2 \cdot \alpha = (3.1\text{kg}) \cdot (.28\text{m})^2 \cdot (4.8\text{rad/s}^2)$
 $\tau = 1.2 \text{ N}\cdot\text{m}$

5) Hollow cylinder \rightarrow mass is concentrated towards the outside

- also $I_{\text{hollow cylinder}} = Mr^2$

$I_{\text{solid cylinder}} = \frac{1}{2}mr^2$

a) solid cylinder, smaller I , easier to get rolling

7) $U_g = K_{rot} + K_{trans}$
 $mgh = \frac{1}{2} I \omega^2 + \frac{1}{2} m v^2 \rightarrow mgh = \frac{1}{2} (m r^2) \omega^2 + \frac{1}{2} m v^2$

a) $K_{trans} = mgh - \frac{1}{2} I \omega^2$

b) $K_{rot} = mgh - \frac{1}{2} m v^2$

c) sphere "I" would decrease, the cylinder is easier to rotate.

8.) Sphere 1 $\Rightarrow I = \frac{2}{5} m r^2 = \frac{2}{5} (1.1 \text{ kg}) (.18 \text{ m})^2 = .0143 \text{ kg} \cdot \text{m}^2$

Sphere 2 $\Rightarrow I = \frac{2}{5} m r^2 = \frac{2}{5} (1.8 \text{ kg}) (.14 \text{ m})^2 = .0141 \text{ kg} \cdot \text{m}^2$

\rightarrow Sphere 2 has a lower I , so it is easier to get rotating. Therefore sphere 2 will reach bottom first (but not by much)

9.) By extending her arms outward, she increases her radius, which cause " I " to increase. Since angular momentum must be conserved, increasing " I " causes " ω " to decrease.

10.) $v = r \omega \rightarrow = (.11 \text{ m}) (4.8 \text{ rad/s}) = .528 \text{ m/s}$

$K_{tot} = K_{rot} + K_{trans} = \frac{1}{2} (m r^2) (\omega)^2 + \frac{1}{2} m v^2$

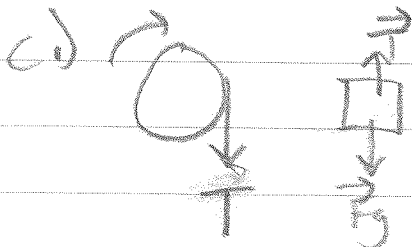
$.5018 \text{ J}$

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$\rightarrow \frac{1}{2} (.36 \text{ kg} \cdot (.11 \text{ m})^2) (4.8 \text{ rad/s})^2 + \frac{1}{2} (.36 \text{ kg}) (.528 \text{ m/s})^2 = .1004 \text{ J}$

11) a) U_g

b) it transforms in K_{trans} for box & K_{rot} for pulley



d) radius of pulley, \rightarrow mass of pulley, and the final angular speed.

$$12) L_i = L_f$$

$$I \omega_i = 2 I \omega_f$$

$$\rightarrow \omega_f = \frac{1}{2} \omega_i$$

$$13) I_{\text{student}} = Mr^2$$

$$I_{\text{mgr}} = \frac{1}{2} m r^2$$

$$L_i = L_f \rightarrow I_{\text{tot}} \omega_i = I_{\text{tot}} \omega_f$$

$$\rightarrow (I_{\text{student}} + I_{\text{mgr}}) \omega_i = (I_{\text{student}} + I_{\text{mgr}}) \omega_f$$

$$\rightarrow \omega_f = \frac{(I_{\text{student}} + I_{\text{mgr}}) \omega_i}{(I_{\text{student}} + I_{\text{mgr}})}$$

$$\rightarrow \omega_f = \frac{(0 + 840 \text{ kg} \cdot \text{m}^2) 1.8 \text{ rad/s}}{(42 \text{ kg} \cdot (3.4 \text{ m})^2 + 840 \text{ kg} \cdot \text{m}^2)} = 1.1 \text{ rad/s}$$

